

Cyber-Physical Systems Seminar

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Machine Learning Methods for Trajectories

- Given
 - Manipulator specifications
 - Obstacles' positions
- Aim
 - Obtaining the possible trajectories using machine learning methods
- Tasks
 - Literature review/reading papers about different machine learning techniques used in Robotics
 - Implementing one or more
 - Comparison of the techniques



(<http://de.schunk.com>)